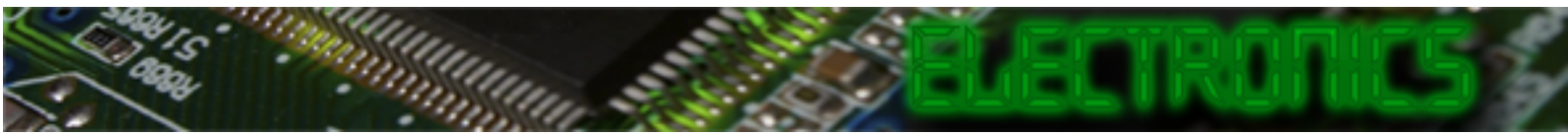
UTouch

Arduino and chipKit Universal TFT touchscreen library

Manual



PREFACE:

This library was made to complement UTFT to provide touch screen functionality.

You can always find the latest version of the library at
http://electronics.henningkarlsen.com/

If you make any modifications or improvements to the code, I would appreciate that you share the code with me so that I might include it in the next release. I can be contacted through **http://electronics.henningkarlsen.com/contact.php**.

For version information, please refer to **version.txt**.

REGARDING CALIBRATION:

All touch screens will have slight variations. It is therefore important that you calibrate your particular touch screen for the best possible performance.

To calibrate your touch screen you will need to run the UTouch_Calibration sketch supplied in the examples of the library.

Before you compile and upload the sketch there are a couple of things you must do.

1. Make sure you have uncommented the correct section for your development board
2. Make sure the UTFT display model code is correct for your display module
3. Make sure the TOUCH_ORIENTATION define is correct. You can find a list of the correct parameter for all the tested displays in the *UTouch_Supported_display_modules* PDF.

Further instructions will be given on screen when you run the sketch.

Remember that if you have more than one touch display module you may have to run the calibration on each module.

Some touch screens, espcially the larger ones (4.3” and larger), have some flaws where they have problems registering touch near the edges. The calibration sketch tries to take this into account when calibrating. Because of this some calibration points takes longer to register.

It is also recommended that you power your Arduino/chipKit using an external power source when running the calibration on 4.3” and larger screens.

Defined Literals:

Orientation
For use with InitTouch()
PORTRAIT: 0
LANDSCAPE: 1

Precision
For use with setPrecision()
PREC_LOW: 1
PREC_MEDIUM: 2
PREC_HI: 3
PREC_EXTREME: 4

Functions:

UTouch(TCLK, TCS, TDIN, TDOUT, IRQ);

The main class of the interface.

Parameters: TCLK: Pin for Touch Clock (D_CLK)
TCS: Pin for Touch Chip Select (D_CS)
TDIN: Pin for Touch Data input (D_DIN)
TDOUT: Pin for Touch Data output (D_OUT)
IRQ: Pin for Touch IRQ (DPenirq)

Usage: `UTouch myTouch(15,10,14,9,8); // Start an instance of the UTouch class`

InitTouch([orientation]);

Initialize the touch screen and set display orientation. If the library is used together with UTFT the orientation should be set to the same orientation for both libraries.

Parameters: orientation: <*optional*>
PORTRAIT
LANDSCAPE (default)

Returns: Nothing

Usage: `myTouch.InitTouch();// Initialize the touch screen`

dataAvailable();

Check to see if new data from the touch screen is waiting.

Parameters: None

Returns: Boolean: true means data is waiting, otherwise false

Usage: `check = myTouch.dataAvailable() // See if data is waiting`

read();

Read waiting data from the touch screen. This function should be called if dataAvailable() is true. Use getX() and getY() to get the coordinates.

Parameters: None

Returns: Nothing

Usage: `myTouch.read(); // Read data from touch screen`

Notes: After calling read(), raw data from the touch screen is available in the variables TP_X and TP_Y. Do not use these if you do not know how to handle the raw data. Use getX() and getY() instead.

getX();

Get the x-coordinate of the last position read from the touch screen.

Parameters: None

Returns: Integer

Usage: `x = myTouch.getX(); // Get the x-coordinate`

getY();

Get the y-coordinate of the last position read from the touch screen.

Parameters: None

Returns: Integer

Usage: `y = myTouch.getY(); // Get the y-coordinate`

setPrecision(precision);

Set the precision of the touch screen.

Parameters: precision: **PREC_LOW, PREC_MEDIUM, PREC_HI, PREC_EXTREME**

Returns: Nothing

Usage: `myTouch.setPrecision(PREC_MEDIUM); // Set precision to medium`

Notes: Higher precision data will take longer to read, so take care when using PREC_HI or PREC_EXTREME with fast-moving input.